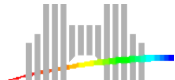


Relaxed method to certify a linear system

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Objective:

- 1 Solve a linear system
 - $A \in \mathbb{R}^{n \times n}$
 - $b \in \mathbb{R}^n$
 - Calculate an approximation $\tilde{x} \in \mathbb{R}^n$ of the exact solution x^* to a linear system $A * x = b$
- 2 Simultaneously bound the error upon this approximation using interval arithmetic
 - $\Delta x = x^* - \tilde{x}$
 - Calculate a small interval \mathbf{e} containing Δx .

Wilkinson, Li & Demmel, Higham, ...

Algorithm 1 (Classical methods of iterative refinement)

Input: $A \in \mathbb{F}^{n \times n}, b \in \mathbb{F}^n$

$\tilde{x} = A \setminus b;$

while(not converged)

$\tilde{r} = b - A * \tilde{x};$

$\tilde{e} = A \setminus \tilde{r};$

$\tilde{x} = \tilde{x} + \tilde{e};$

end

Iterative refinement: switch to interval arithmetic

Notations: x^* exact solution, \tilde{x} floating point approximation, \mathbf{x} an interval containing the exact solution

Algorithm 2 (Interval iterative refinement)

Input: $A \in \mathbb{F}^{n \times n}$, $b \in \mathbb{F}^n$

$\tilde{x} = A \setminus b$;

while(not converged)

$\mathbf{r} = [b - A * \tilde{x}]$; % $A * (x^* - \tilde{x}) \in \mathbf{r}$

$\mathbf{e} = A \setminus \mathbf{r}$; % $x^* - \tilde{x} \in \mathbf{e}$

$\tilde{x} = \tilde{x} + \text{mid}(\mathbf{e})$;

end

$$A * e = r$$

Principle: precondition the system by an approximative inverse R of A .

$$\begin{aligned} K &= [R * A] & z &= R * r \\ K * e &= z \end{aligned}$$

Method: Interval iterative improvement

- do not solve directly the interval system.
- consider it as constraints to improve the error bound

$$\begin{aligned} e' &= e \cap (K \setminus z) \\ &= \{ \tilde{e} \in e \mid \exists \tilde{K} \in K, \exists \tilde{z} \in z : \tilde{K} * \tilde{e} = \tilde{z} \} \end{aligned}$$

Residual system (2)

Rough initial solution by **Simplified Neumaier proposition** (CUP 1990)¹:

If $\langle \mathbf{K} \rangle u \geq v > 0$ for $u \geq 0$ then

$$\mathbf{K}^{-1} \mathbf{z} \subseteq \|\mathbf{z}\|_v * [-u, u].$$

Where

- $\langle \mathbf{K} \rangle$ is the comparison matrix of \mathbf{K} :

$$\begin{aligned}\langle \mathbf{K} \rangle_{i,i} &= \min(|\mathbf{K}_{i,i}|) \\ \langle \mathbf{K} \rangle_{i,j \neq i} &= -\max(|\mathbf{K}_{i,j}|)\end{aligned}$$

- $\|\mathbf{z}\|_v = \max_i (|\mathbf{z}_i| / |v_i|)$

¹page 121, Arnold Neumaier, *Interval Methods for Systems of Equations*

Interval Gauss-Seidel iterations

$$(\mathbf{K} \setminus \mathbf{z}) \cap \mathbf{e} = \{\tilde{\mathbf{e}} \in \mathbf{e} \mid \exists \tilde{\mathbf{K}} \in \mathbf{K}, \exists \tilde{\mathbf{z}} \in \mathbf{z} : \tilde{\mathbf{K}} * \tilde{\mathbf{e}} = \tilde{\mathbf{z}}\}$$

$$\tilde{K}_{i,1}\tilde{e}_1 + \dots + \tilde{K}_{i,i-1}\tilde{e}_{i-1} + \tilde{K}_{i,i}\tilde{e}_i + \tilde{K}_{i,i+1}\tilde{e}_{i+1} + \dots + \tilde{K}_{i,n}\tilde{e}_n = z_i$$

$$\tilde{e}_i = \left(\tilde{z}_i - \sum_{j=1}^{i-1} \tilde{K}_{i,j}\tilde{e}_j - \sum_{j=i+1}^n \tilde{K}_{i,j}\tilde{e}_j \right) / \tilde{K}_{i,i}$$

$$\mathbf{e}'_i \subseteq \left(z_i - \sum_{j=1}^{i-1} K_{i,j}e'_j - \sum_{j=i+1}^n K_{i,j}e_j \right) / K_{i,i} \cap e_i$$

$$(\mathbf{K} \setminus \mathbf{z}) \cap \mathbf{e} = \{\tilde{\mathbf{e}} \in \mathbf{e} \mid \exists \tilde{\mathbf{K}} \in \mathbf{K}, \exists \tilde{\mathbf{z}} \in \mathbf{z} : \tilde{\mathbf{K}} * \tilde{\mathbf{e}} = \tilde{\mathbf{z}}\}$$

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Algorithm 3 (Interval iterative refinement)

Input: $A \in \mathbb{F}^{n \times n}, b \in \mathbb{F}^n$

$\tilde{x} = A \setminus b;$

$R = \text{inv}(A);$

$K = [R * A];$

$z = R * [b - A * \tilde{x}];$

*Calculate an initial solution to $K * e = z;$*

while(not converged)

*Apply at most 5 interval Gauss-Seidel iterations on $K * e = z;$*

$\tilde{x} = \tilde{x} + \text{mid}(e); \quad e = e - \text{mid}(e) \quad \% \quad \tilde{x} + e \ni x^*$

$z = R * [b - A * \tilde{x}];$

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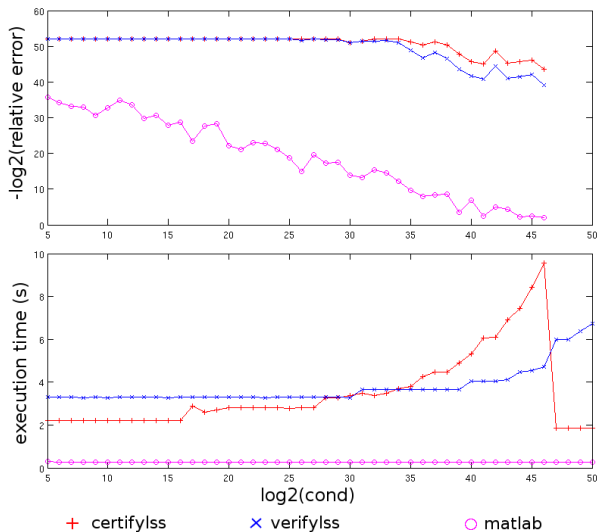
$z = R * [b - A * \tilde{x}];$

end

Experimental Results

System rank: 1000

$$b = [1, \dots, 1]^T$$



Problem: Each Gauss-Seidel/Gauss refinement costs $\mathcal{O}(n^2)$ interval operations \rightarrow execution time increases rapidly when number of iterations increases.

Example using Intlab (INTerval LABoratory)

iA interval matrix of size 1000x1000, **ib**: interval vector of size 1000.

*tic; A * A; toc* \rightarrow 0.550s

*tic; A * b; toc* \rightarrow 0.004s

*tic; iA * ib; toc* \rightarrow 0.14s

\Rightarrow *factor* > 30

Special cases of interval calculations

Let x , y and z be three intervals and y, z are centered by zero

$$\rightarrow \underline{y} = -\bar{y}, \underline{z} = -\bar{z},$$

Addition:

$$\begin{aligned} tmp &\triangleq \bar{y} + \bar{z} \\ y + z &= \text{infsup}(-tmp, tmp) \end{aligned}$$

Multiplication:

$$\begin{aligned} tmp &\triangleq \bar{y} * \text{mag}(x) \\ x * y &= \text{infsup}(-tmp, tmp) \end{aligned}$$

Fused Multiplier-Adder

$$\begin{aligned} tmp &\triangleq \bar{y} * \text{mag}(x) + \bar{z} \\ x * y + z &= \text{infsup}(-tmp, tmp) \end{aligned}$$

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Let x , y and z be three intervals and y, z are centered by zero

$$\rightarrow \underline{y} = -\bar{y}, \underline{z} = -\bar{z},$$

Addition:

$$\begin{aligned} y + z &= \text{infsup}(\underline{y} + \underline{z}, \bar{y} + \bar{z}) \\ &= \text{infsup}(-(\bar{y} + \bar{z}), \bar{y} + \bar{z}) \end{aligned}$$

$$tmp \triangleq \bar{y} + \bar{z}$$

$$y + z = \text{infsup}(-tmp, tmp)$$

Multiplication:

$$tmp \triangleq \bar{y} * \text{mag}(x)$$

$$x * y = \text{infsup}(-tmp, tmp)$$

Fused Multiplier-Adder

$$tmp \triangleq \bar{y} * \text{mag}(x) + \bar{z}$$

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Special cases of interval calculations

Let \underline{x} , \underline{y} and \underline{z} be three intervals and $\underline{y}, \underline{z}$ are centered by zero

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Addition:

$$\begin{aligned} tmp &\triangleq \bar{y} + \bar{z} \\ \underline{y} + \underline{z} &= \text{infsup}(-tmp, tmp) \end{aligned}$$

Multiplication:

$$\begin{aligned} \underline{\underline{x*y}} &= \min(\underline{x} * \underline{y}, \underline{x} * \bar{y}, \bar{x} * \underline{y}, \bar{x} * \bar{y}) \\ \overline{\underline{x*y}} &= \max(\underline{x} * \underline{y}, \underline{x} * \bar{y}, \bar{x} * \underline{y}, \bar{x} * \bar{y}) \end{aligned}$$

$$\begin{aligned} tmp &\triangleq \bar{y} * \text{mag}(\underline{x}) \\ \underline{x} * \underline{y} &= \text{infsup}(-tmp, tmp) \end{aligned}$$

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Let \underline{x} , \underline{y} and \underline{z} be three intervals and $\underline{y}, \underline{z}$ are centered by zero

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Addition:

$$\begin{aligned} tmp &\triangleq \bar{y} + \bar{z} \\ \underline{y} + \underline{z} &= \text{infsup}(-tmp, tmp) \end{aligned}$$

Multiplication:

$$\begin{aligned} \underline{x} * \underline{y} &= \min(-\bar{y} * |\underline{x}|, -\bar{y} * |\bar{x}|) \\ \overline{x * y} &= \max(\bar{y} * |\underline{x}|, \bar{y} * |\bar{x}|) \end{aligned}$$

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Let x , y and z be three intervals and y, z are centered by zero

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Multiplication:

$$\begin{aligned} \underline{x*y} &= -\bar{y} * \max(|\underline{x}|, |\bar{x}|) \\ \overline{x*y} &= \bar{y} * \max(|\underline{x}|, |\bar{x}|) \end{aligned}$$

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$$\begin{aligned} tmp &\triangleq \bar{y} + \bar{z} \\ y + z &= \text{infsup}(-tmp, tmp) \end{aligned}$$

Multiplication:

$$\begin{aligned} \overline{x*y} &= -\bar{y} * \text{mag}(x) \\ \underline{x*y} &= \bar{y} * \text{mag}(x) \end{aligned}$$

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Special cases: matrix calculations

Let \mathbf{b} be an interval vector.

If \mathbf{a} is an interval vector centered by zero

$$\begin{aligned} tmp &\triangleq \bar{\mathbf{a}} \circ \text{mag}(\mathbf{b}) \\ \mathbf{a} \circ \mathbf{b} &= \text{infsup}(-tmp, tmp) \end{aligned}$$

If \mathbf{A} is a interval matrix centered by zero

$$\begin{aligned} tmp &\triangleq \bar{\mathbf{A}} * \text{mag}(\mathbf{b}) \\ \mathbf{A} * \mathbf{b} &= \text{infsup}(-tmp, tmp) \end{aligned}$$

Relaxed Gauss-Seidel iterations

Calculate a truncated solution to $\mathbf{K}\mathbf{e} = \mathbf{z}$.

Let \mathbf{D} , \mathbf{L} , \mathbf{U} be the diagonal, lower part and upper part of \mathbf{K} .

Jacobi: $\mathbf{D} * \mathbf{e}' = \mathbf{z} - \mathbf{U} * \mathbf{e} - \mathbf{L} * \mathbf{e}$

Gauss-Seidel: $\mathbf{D} * \mathbf{e}' = \mathbf{z} - \mathbf{U} * \mathbf{e} - \mathbf{L} * \mathbf{e}'$

\mathbf{L} , \mathbf{U} are close to zero \Rightarrow Inflate \mathbf{L} and \mathbf{U} so that they are centered by zero:

$$\mathbf{U}_i = \text{infsup}(-\text{mag}(\mathbf{U}), \text{mag}(\mathbf{U}))$$

$$\mathbf{L}_i = \text{infsup}(-\text{mag}(\mathbf{L}), \text{mag}(\mathbf{L}))$$

$\Rightarrow \mathbf{U} \subseteq \mathbf{U}_i, \mathbf{L} \subseteq \mathbf{L}_i$

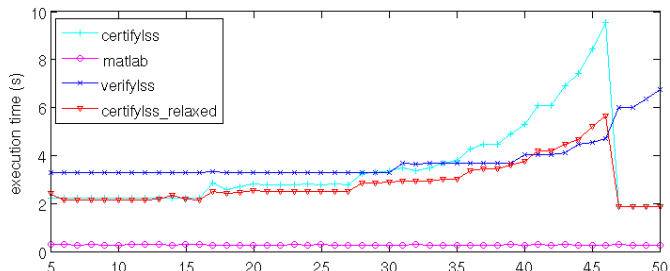
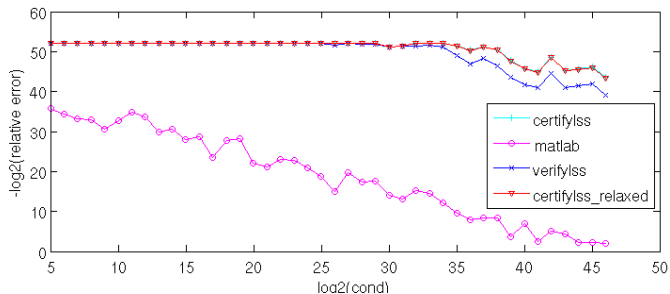
Relaxed Gauss-Seidel iteration

$$\mathbf{D} * \mathbf{e}'' = \mathbf{z} - \mathbf{U}_i * \mathbf{e} - \mathbf{L}_i * \mathbf{e}''$$

$$\mathbf{e}' \subseteq \mathbf{e}''$$

Relaxed method: Results

System rank: 1000 $b = [1, \dots, 1]^T$



- Combining the floating-point refinement and the interval iterations, our method provides accurate results when the condition number of the coefficient matrix is much smaller than 2^p (p is the working precision).
- With the proposed relaxation technique, we managed to reduce a lot the execution time of interval refinement part.

In the future: Expand to the other problems

- Linear system of inequalities
- Nonlinear system
- Numerical constraint system, using the techniques of constraint propagation

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